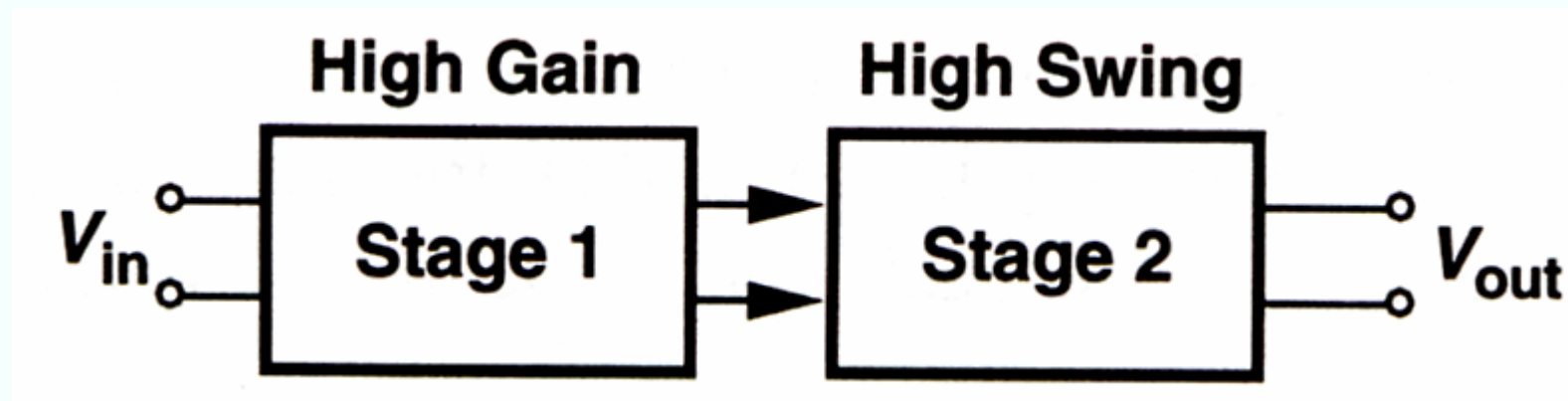


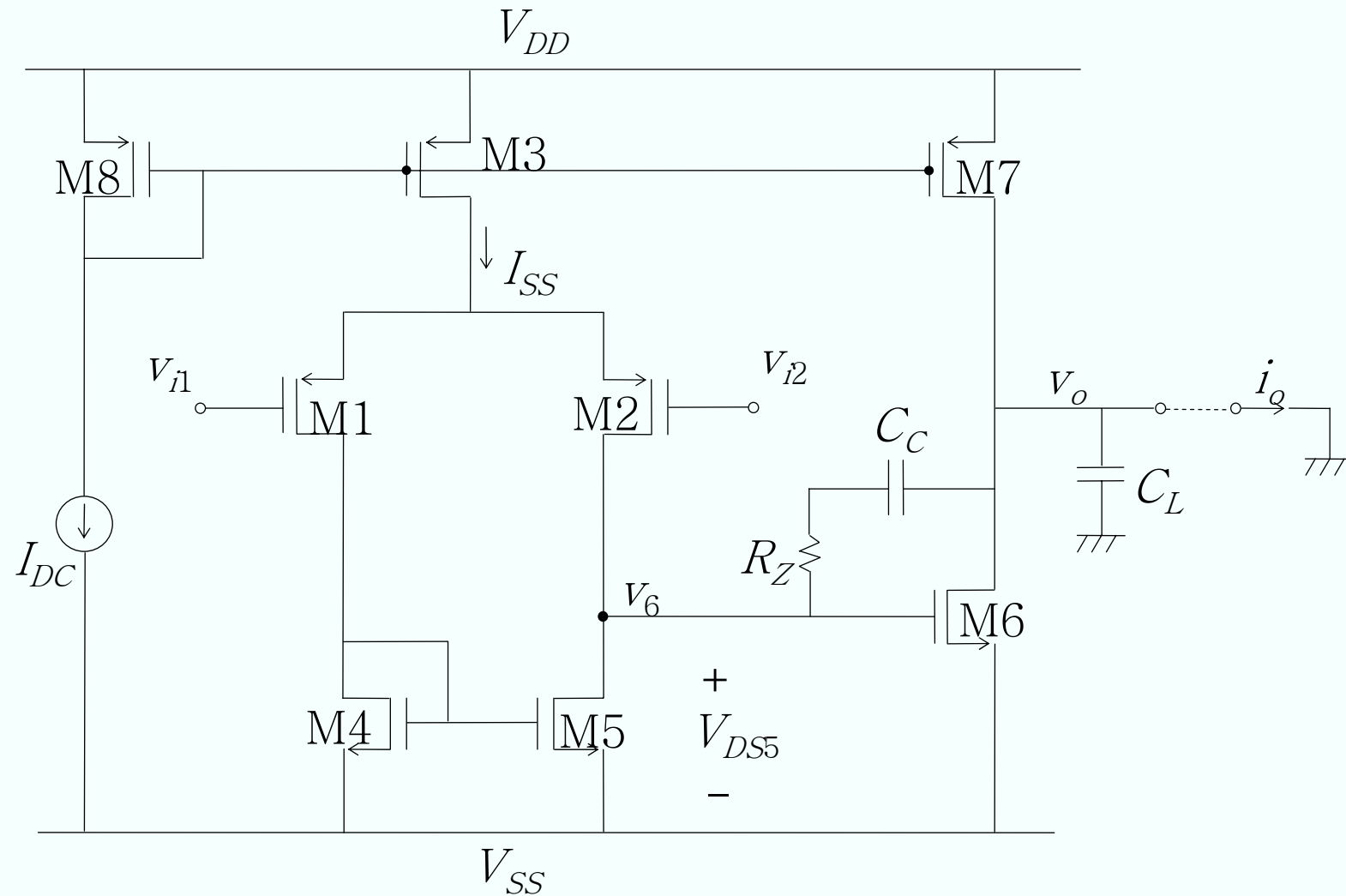
## 2. 2-stage OP amp

**2-stage OP amp : pro → high gain + high output swing**



**2-stage OP amp :**

**con → requires frequency compensation (usually Miller(pole-splitting) frequency compensation)**

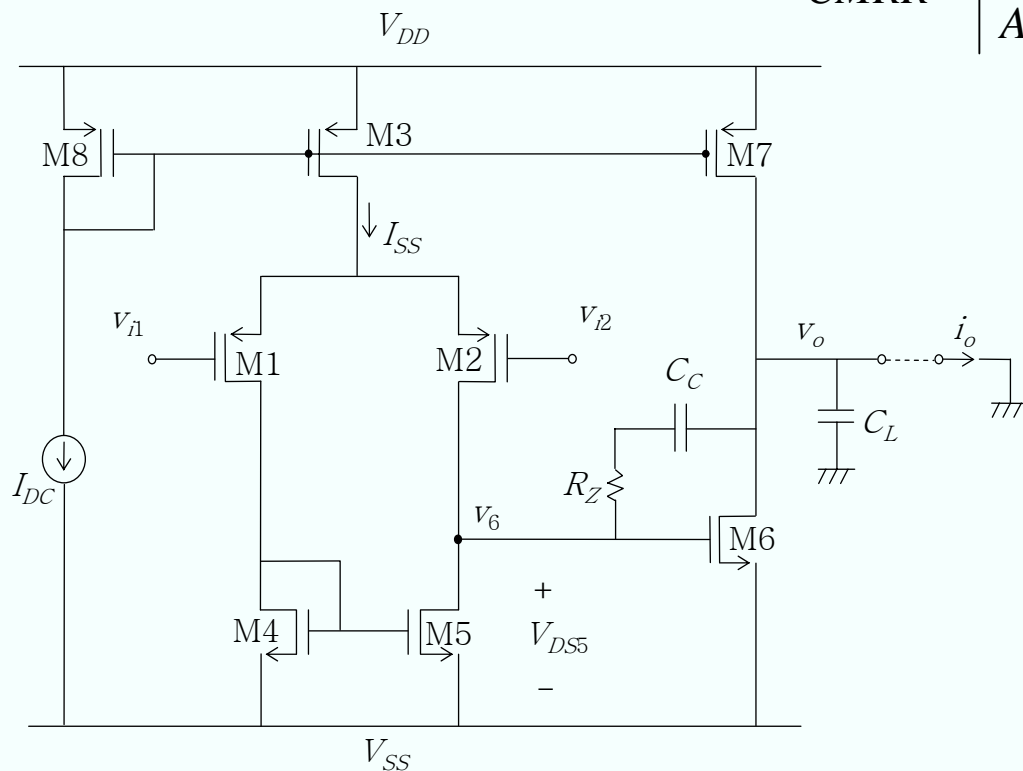
**Fig 9.1.1** 2-stage CMOS OP amp

## Small-signal gain

$$A_{vd} = A_{vd1} \cdot A_{v2} = -g_{m1} \cdot (r_{o2} \parallel r_{o5}) \cdot g_{m6} \cdot (r_{o6} \parallel r_{o7})$$

$$A_{vc} = \frac{(r_{o2} \parallel r_{o5})}{(2r_{o3}) \cdot (g_{m4} \cdot (r_{o1} \parallel r_{o4}))} \cdot g_{m6} \cdot (r_{o6} \parallel r_{o7})$$

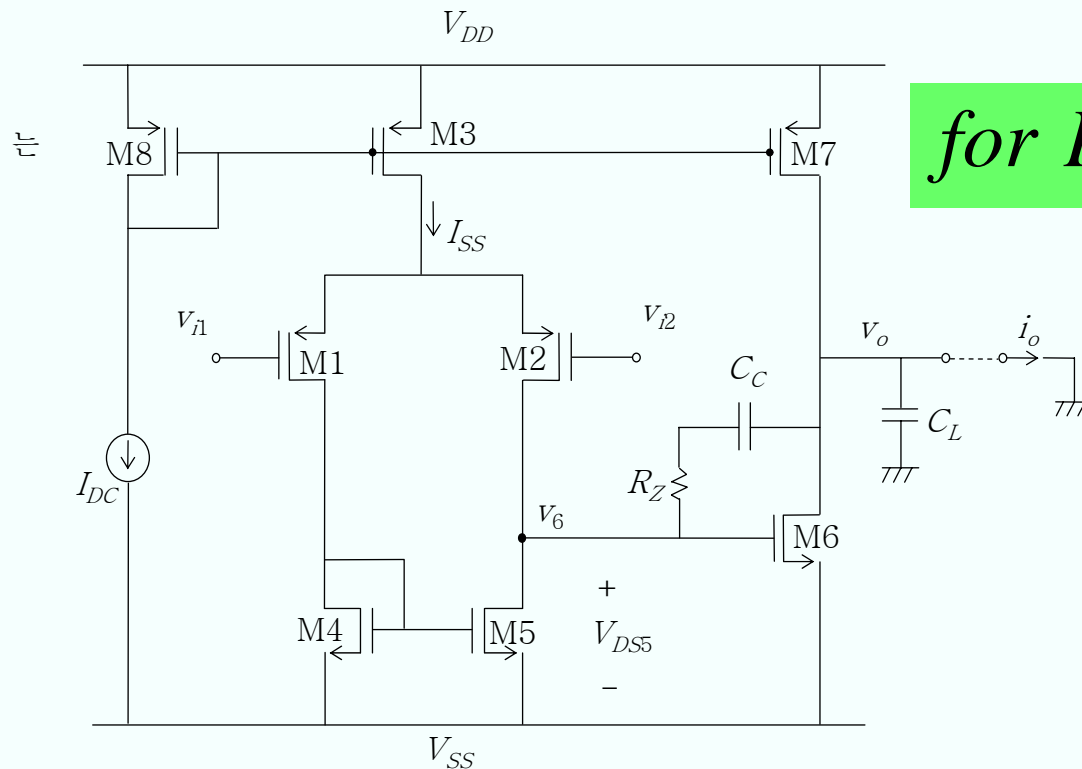
$$CMRR = \left| \frac{A_{vd}}{A_{vc}} \right| = \left| \frac{A_{vd1}}{A_{vc1}} \right| = (2g_{m1}r_{o3}) \cdot (g_{m4} \cdot (r_{o1} \parallel r_{o4}))$$



## Systematic input offset voltage

$$V_{I1} = V_{I2} = 0 \quad \rightarrow \quad V_{DS5} = V_{GS4}$$

$$I_{D6} \neq I_{D7} \quad \rightarrow \quad \text{Systematic offset 발생}$$



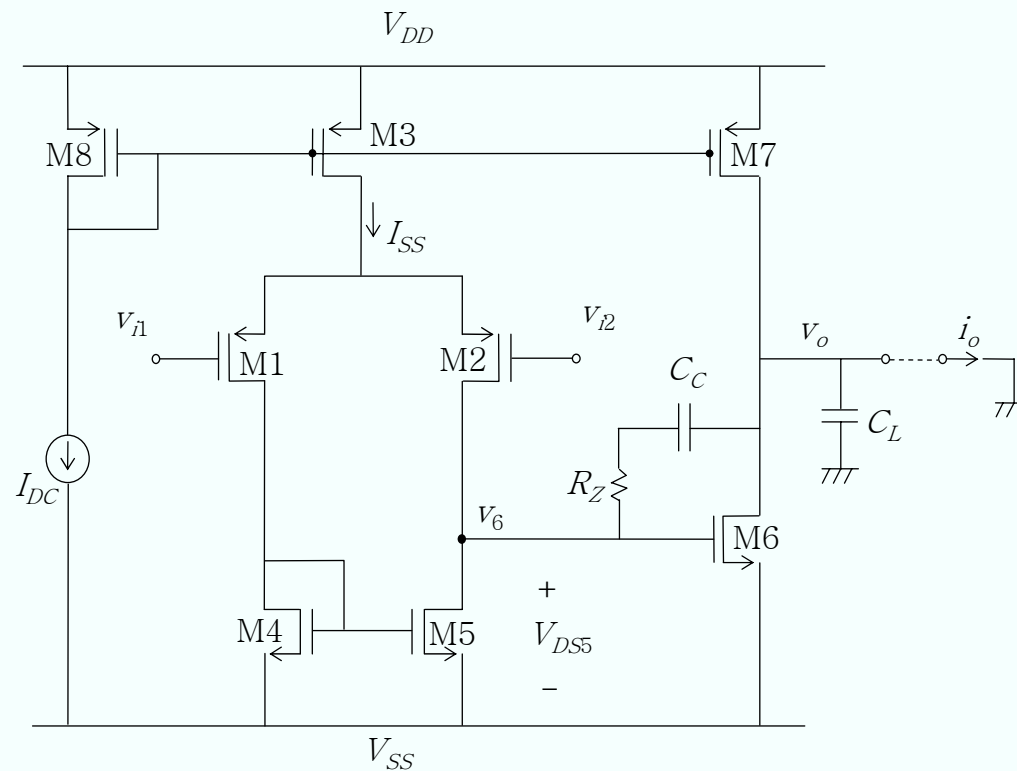
for  $I_{D6} = I_{D7}$

$$\frac{(W/L)_6}{(W/L)_4} = \frac{(W/L)_7}{0.5 \cdot (W/L)_3}$$

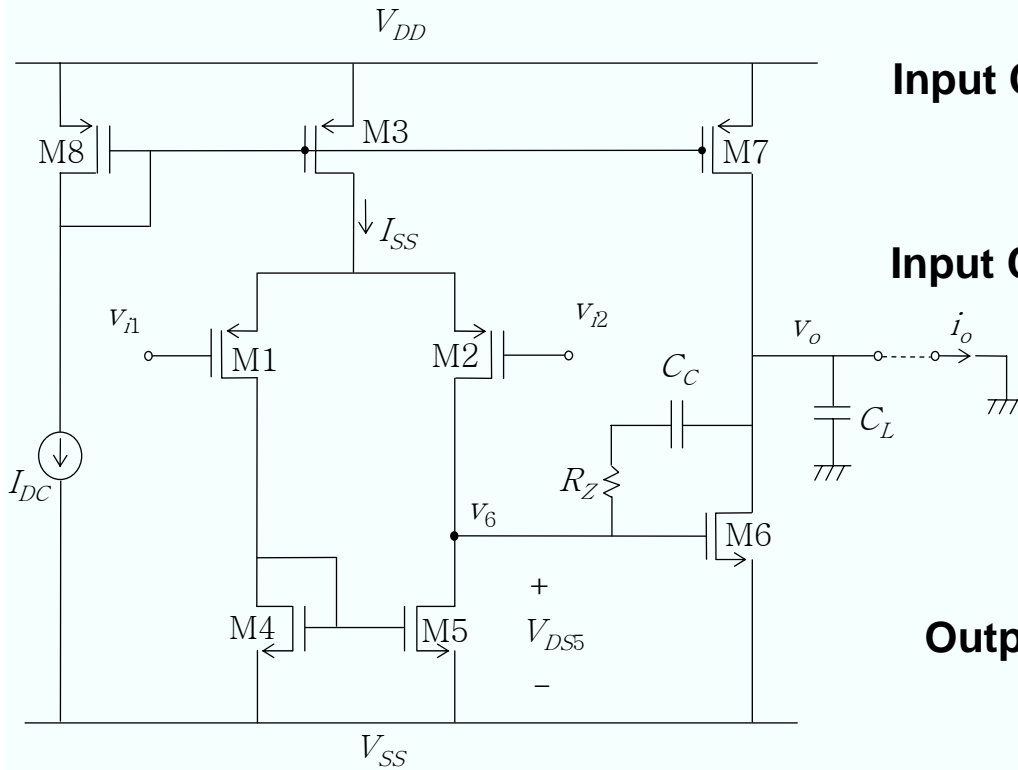
**No systematic offset**

## Random input offset voltage

$$V_{os} = \Delta V_{THn1,2} + \Delta V_{THp4,5} \cdot \frac{g_{m4,5}}{g_{m1,2}} + \frac{(V_{GS} - V_{THn})_{1,2}}{2} \cdot \left\{ -\frac{\Delta(W/L)_{1,2}}{(W/L)_{1,2}} + \frac{\Delta(W/L)_{4,5}}{(W/L)_{4,5}} \right\} + \frac{\Delta V_{GS6}}{A_{vd1}}$$



## Active input common mode voltage range & Linear output voltage range



$$\text{Input CM min: } V_{SS} + V_{THn4} + V_{DSAT4} - |V_{THp1}|$$

$$\text{Input CM max: } V_{DD} - |V_{DSAT3}| - |V_{DSAT1}| - |V_{THp1}|$$

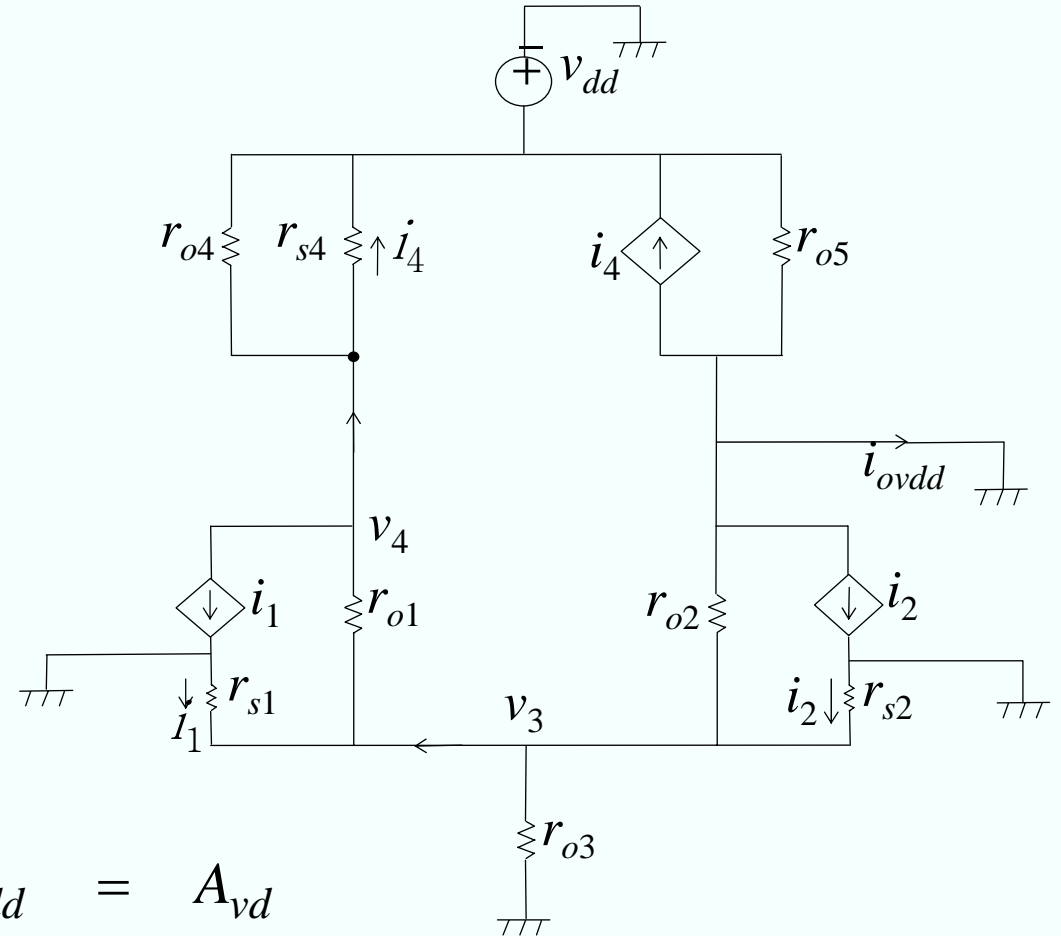
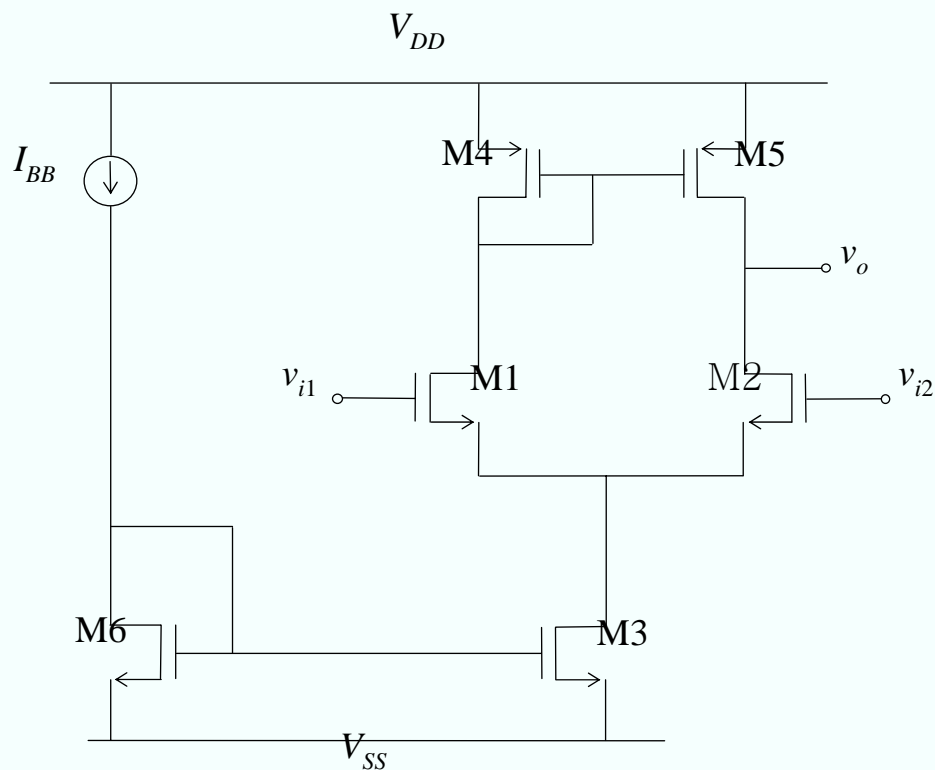
**Input CM: shifted toward Vss**

$$\text{Output min: } (V_{SS} + V_{DSAT6})$$

$$\text{Output max: } (V_{DD} - |V_{DSAT7}|)$$

**Large output swing**

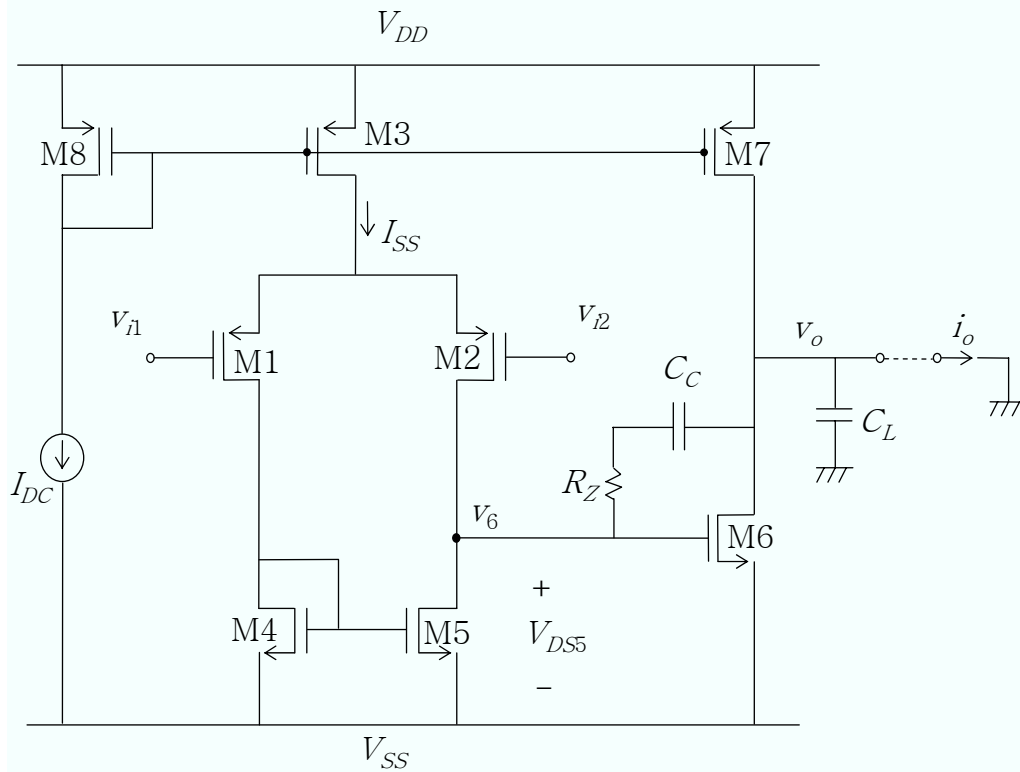
## PSRR (diff pair) review



$$v_o = v_{dd} \quad PSRR^+ \triangleq \frac{A_{vd}}{A_{vdd}} = A_{vd}$$

$$PSRR^- \triangleq \left| \frac{A_{vd}}{A_{vss}} \right| = (2g_{m1}r_{o3}) \cdot \{g_{m4}(r_{o1} \parallel r_{o4})\} = CMRR$$

**Good PSRR-**

PSRR : not good due to 2<sup>nd</sup> stage

$$\frac{v_o}{v_{dd}} = \left\{ A_{vc1} \cdot g_{m6} + \frac{1}{r_{o7}} \right\} \cdot (r_{o6} \parallel r_{o7})$$

$$PSRR^+ = \frac{g_{m1} \cdot (r_{o2} \parallel r_{o5}) \cdot g_{m6}}{-\frac{g_{m6} \cdot (r_{o2} \parallel r_{o5})}{2r_{o3} \cdot g_{m4} \cdot (r_{o1} \parallel r_{o4})} + \frac{1}{r_{o7}}}$$

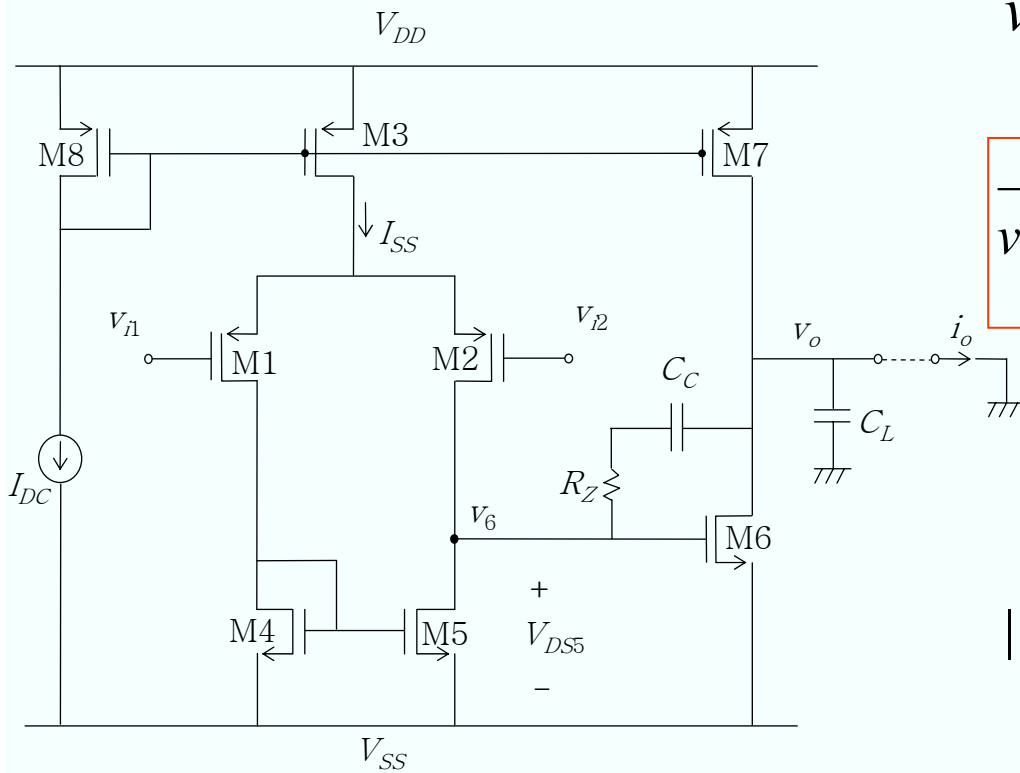
$$= \frac{1}{-\frac{1}{(CMRR)} + \frac{1}{A_{vd}} \cdot \left( \frac{r_{o6} \parallel r_{o7}}{r_{o7}} \right)}$$

$$v_o = \frac{r_{o7}}{r_{o6} + r_{o7}} \cdot v_{ss} = \frac{(r_{o6} \parallel r_{o7})}{r_{o6}} \cdot v_{ss}$$

$$PSRR^- = \frac{A_{vd}}{\left( \frac{r_{o6} \parallel r_{o7}}{r_{o6}} \right)} = A_{vd1} \cdot g_{m6} r_{o6}$$

**Both PSRR+, PSRR- : close to A<sub>vd</sub>**

## Equivalent input noise voltage



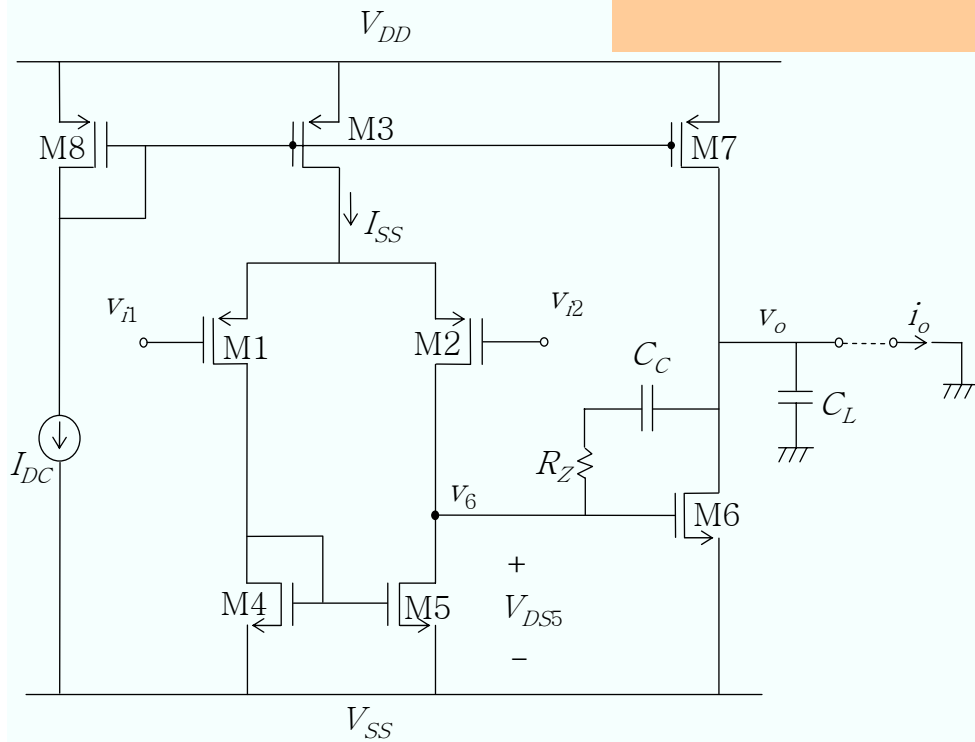
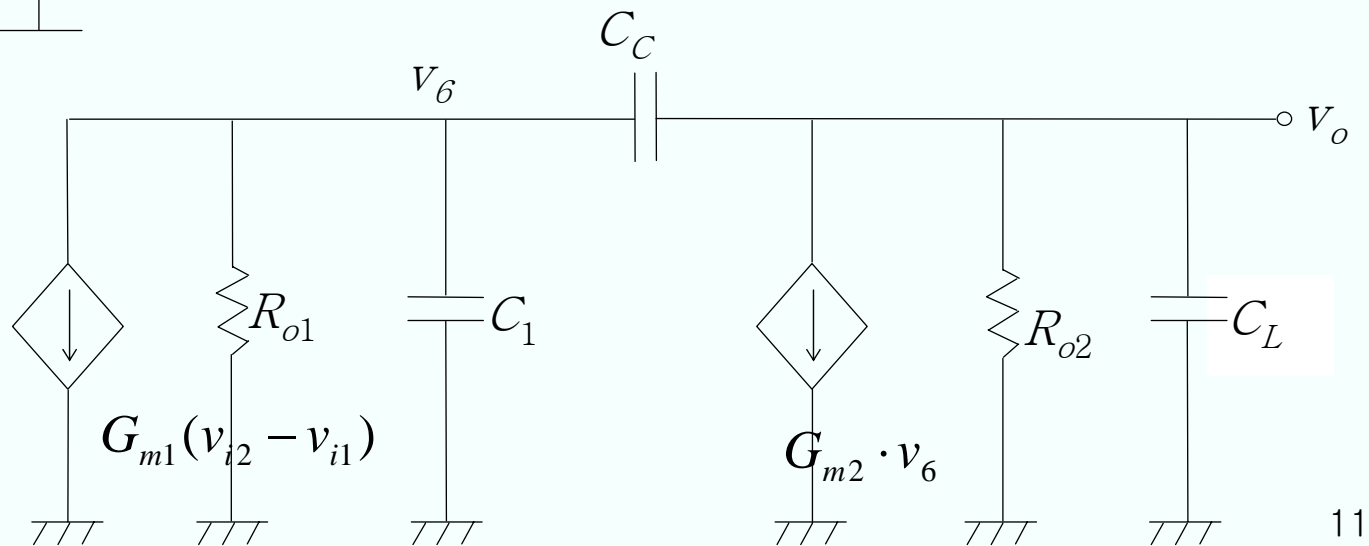
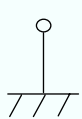
$$\overline{v_{ieqn}^2} = \overline{v_{ieqn1}^2} + \frac{\overline{v_{ieqn2}^2}}{(A_{vd1})^2}$$

$$\overline{v_{ieqn}^2} = \overline{v_{gn1}^2} + \overline{v_{gn2}^2} + \left(\frac{g_{m5}}{g_{m1}}\right)^2 \cdot \left(\overline{v_{gn4}^2} + \overline{v_{gn5}^2}\right)$$

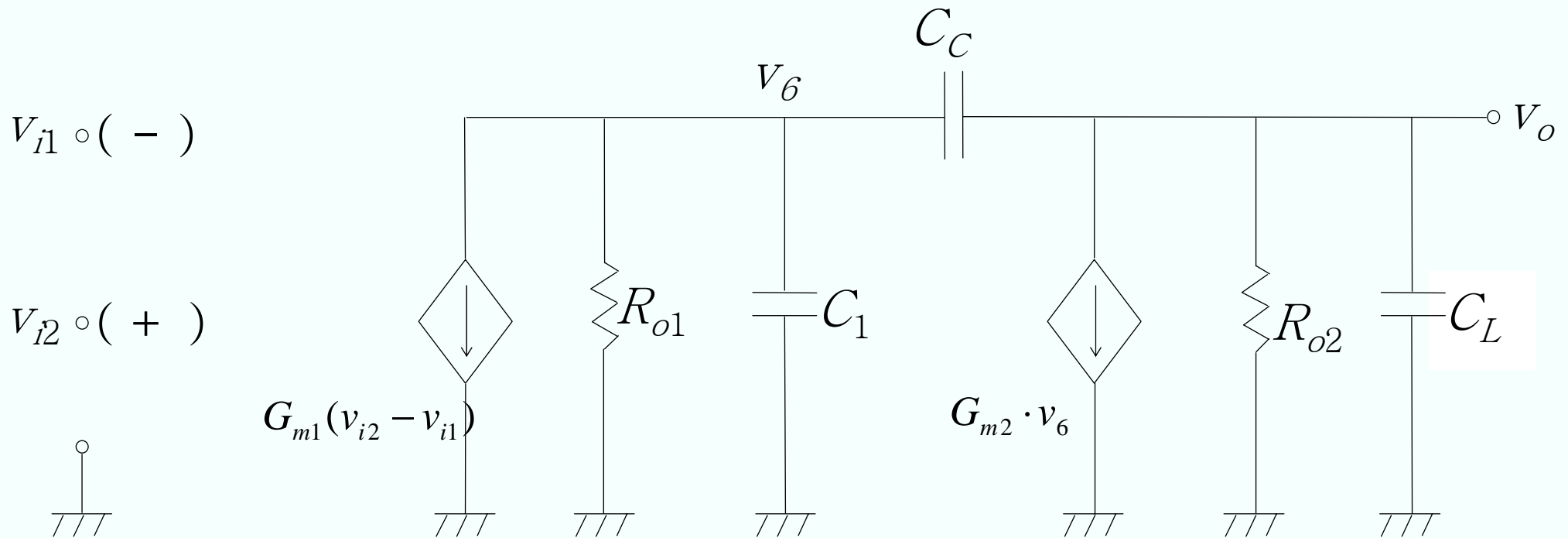
$$|V_{ieqn}(f)|^2 = \frac{16}{3} \cdot kT \cdot \frac{1}{g_{m1}} \cdot \left(1 + \frac{g_{m5}}{g_{m1}}\right)$$

To reduce noise → reduce \$g\_{m5}\$ → increase \$V\_{DSAT5}\$

## Frequency response


 $v_{i1} \circ (-)$ 
 $v_{i2} \circ (+)$ 


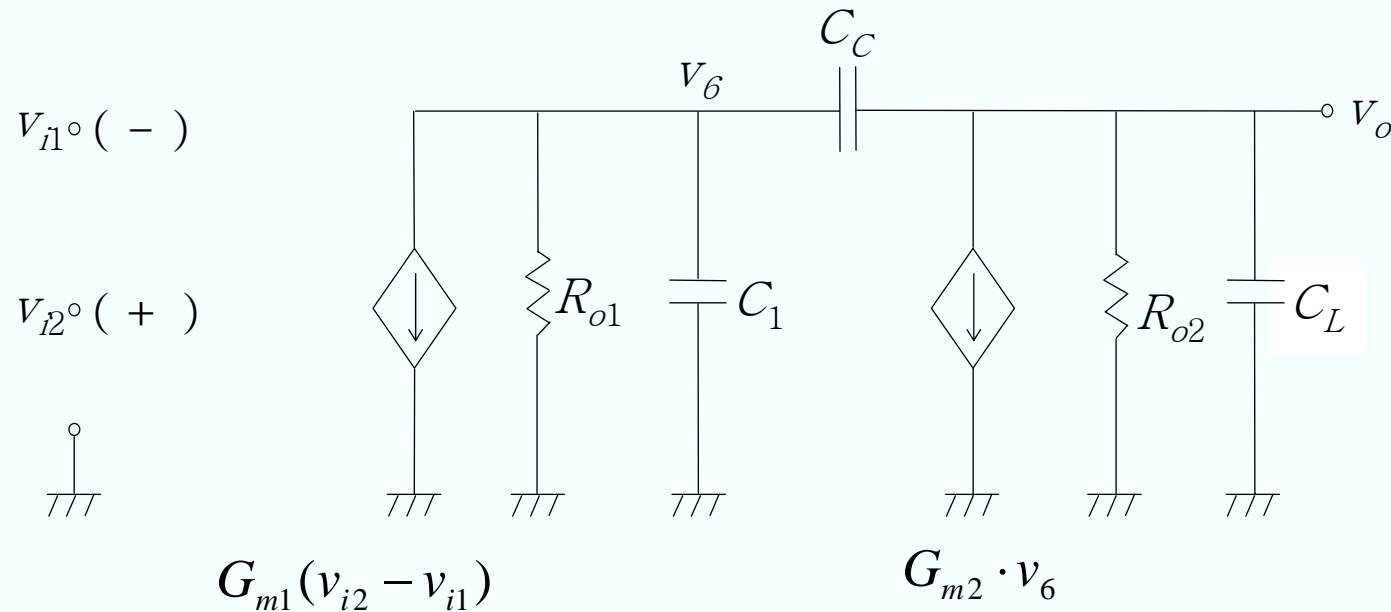
## Frequency response

KCL at  $v_6$  and  $v_o$  nodes

$$G_{m1} \cdot (v_{i2} - v_{i1}) + \left\{ s(C_1 + C_C) + \frac{1}{R_{o1}} \right\} \cdot v_6 - sC_C \cdot v_o = 0$$

$$(G_{m2} - sC_C) \cdot v_6 + \left\{ s(C_L + C_C) + \frac{1}{R_{o2}} \right\} \cdot v_o = 0$$

## Frequency response



$$A_{dv}(s) = \frac{v_o}{v_{i2} - v_{i1}} = \frac{(G_{m1}R_{o1}) \cdot (G_{m2}R_{o2}) \cdot (1 - sC_C/G_{m2})}{\left[ 1 + s \cdot \{C_L R_{o2} + C_1 R_{o1} + C_C \cdot (G_{m2}R_{o2}R_{o1} + R_{o1} + R_{o2})\} \right. \\ \left. + s^2 \cdot \{C_1 C_L + (C_1 + C_L) C_C\} \cdot R_{o1} R_{o2} \right]}$$

## Frequency response

$$A_{dv}(s) = \frac{v_o}{v_{i2} - v_{i1}} = \frac{(G_{m1}R_{o1}) \cdot (G_{m2}R_{o2}) \cdot (1 - sC_C/G_{m2})}{\left[ \begin{array}{l} 1 + s \cdot \{C_L R_{o2} + C_1 R_{o1} + C_C \cdot (G_{m2} R_{o2} R_{o1} + R_{o1} + R_{o2})\} \\ + s^2 \cdot \{C_1 C_L + (C_1 + C_L) C_C\} \cdot R_{o1} R_{o2} \end{array} \right]}$$

$$A_{dv}(s) = \frac{A_{dv}(0) \cdot \left(1 - \frac{s}{z_1}\right)}{\left(1 - \frac{s}{p_1}\right) \cdot \left(1 - \frac{s}{p_2}\right)} \approx \frac{A_{dv}(0) \cdot \left(1 - \frac{s}{z_1}\right)}{1 - \frac{s}{p_1} + \frac{s^2}{p_1 p_2}}$$

Dominant pole approximation:

$$|p_1| \ll |p_2|$$

$$p_1 = \frac{-1}{C_C \cdot (G_{m2} R_{o2} R_{o1} + R_{o1} + R_{o2}) + C_L R_{o2} + C_1 R_{o1}} \approx \frac{-1}{R_{o1} \cdot G_{m2} R_{o2} \cdot C_C}$$

$$p_2 = \frac{+1}{p_1 \cdot \{C_C(C_1 + C_L) + C_1 C_L\} R_{o1} R_{o2}} = \frac{-G_{m2} C_C}{C_C(C_1 + C_L) + C_1 C_L} \quad z_1 = + \frac{G_{m2}}{C_C}$$

$$A_{dv}(s) = \frac{A_{dv}(0) \cdot \left(1 - \frac{s}{z_1}\right)}{\left(1 - \frac{s}{p_1}\right) \cdot \left(1 - \frac{s}{p_2}\right)} \approx \frac{A_{dv}(0) \cdot \left(1 - \frac{s}{z_1}\right)}{1 - \frac{s}{p_1} + \frac{s^2}{p_1 p_2}}$$

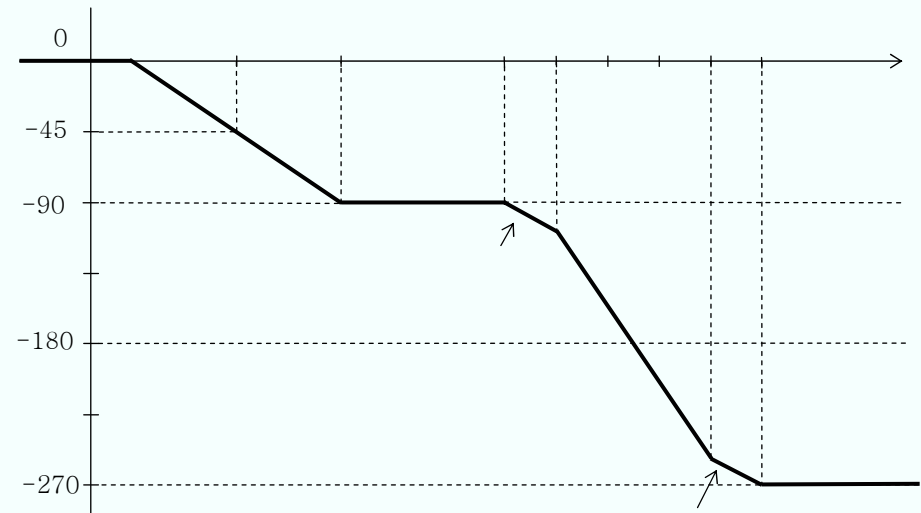
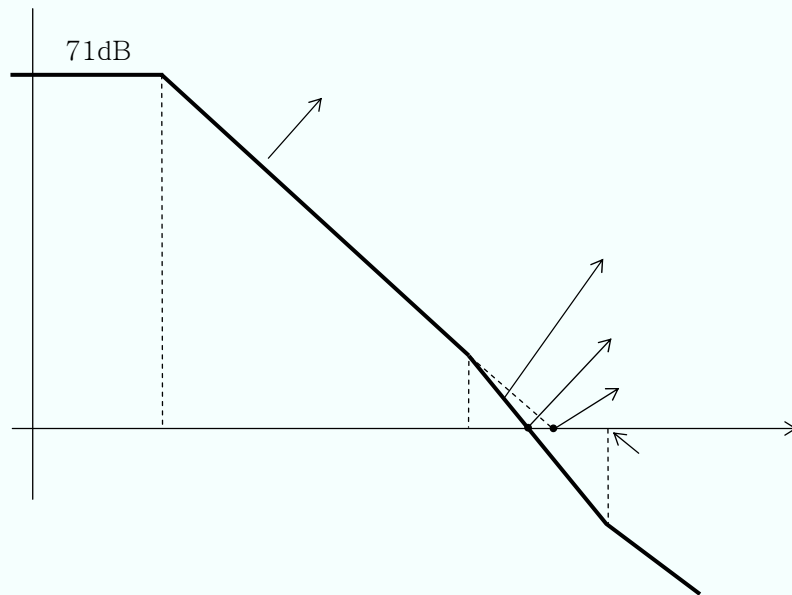
Table 9.1.1 Frequency characteristics of 2-stage OP amp for  $C_L > C_C \gg C_1$

Parameters	$ A_{dv}(0) $	$p_1$	$p_2$	$z_1$	$\omega_T$
Equations	$G_{m1}R_{o1} \cdot G_{m2}R_{o2}$	$\frac{-1}{R_{o1} \cdot G_{m2}R_{o2} \cdot C_C}$	$-\frac{G_{m2}}{C_L}$	$+\frac{G_{m2}}{C_C}$	$\frac{G_{m1}}{C_C}$

$$G_{m1} = 1.76 \times 10^{-3} \quad G_{m2} = 1.94 \times 10^{-3} \quad R_{o1} = 64.8 K\Omega \quad R_{o2} = 15.5 K\Omega \quad C_L = 10 pF \quad C_C = 2 pF$$

$$A_{dv}(0) = 3425 (71 dB) \quad p_1 = -257 K \cdot rad/sec \quad p_2 = -194 M \cdot rad/sec$$

$$z_1 = +970 M \cdot rad/sec \quad \omega_T = 880 M \cdot rad/sec$$



$$ph\{A_{dv}(j\omega_{0dB})\} = -90^\circ - ph\left(1 - \frac{j\omega_{0dB}}{p_2}\right) + ph\left(1 - \frac{j\omega_{0dB}}{z_1}\right) = -178^\circ$$

phase margin(unity-gain fb) = 2 deg → requires frequency compensation

**Cases which require frequency compensation****2-stage OP amp: Cascade of two gain stages****Non-dominant pole > Unity gain frequency**

$$\frac{1}{R_{o1}C_1} < \frac{G_{m1}R_{o1} \cdot G_{m2}}{C_L}$$

$$G_{m1}R_{o1} \cdot G_{m2}R_{o1} > \frac{C_L}{C_1}$$

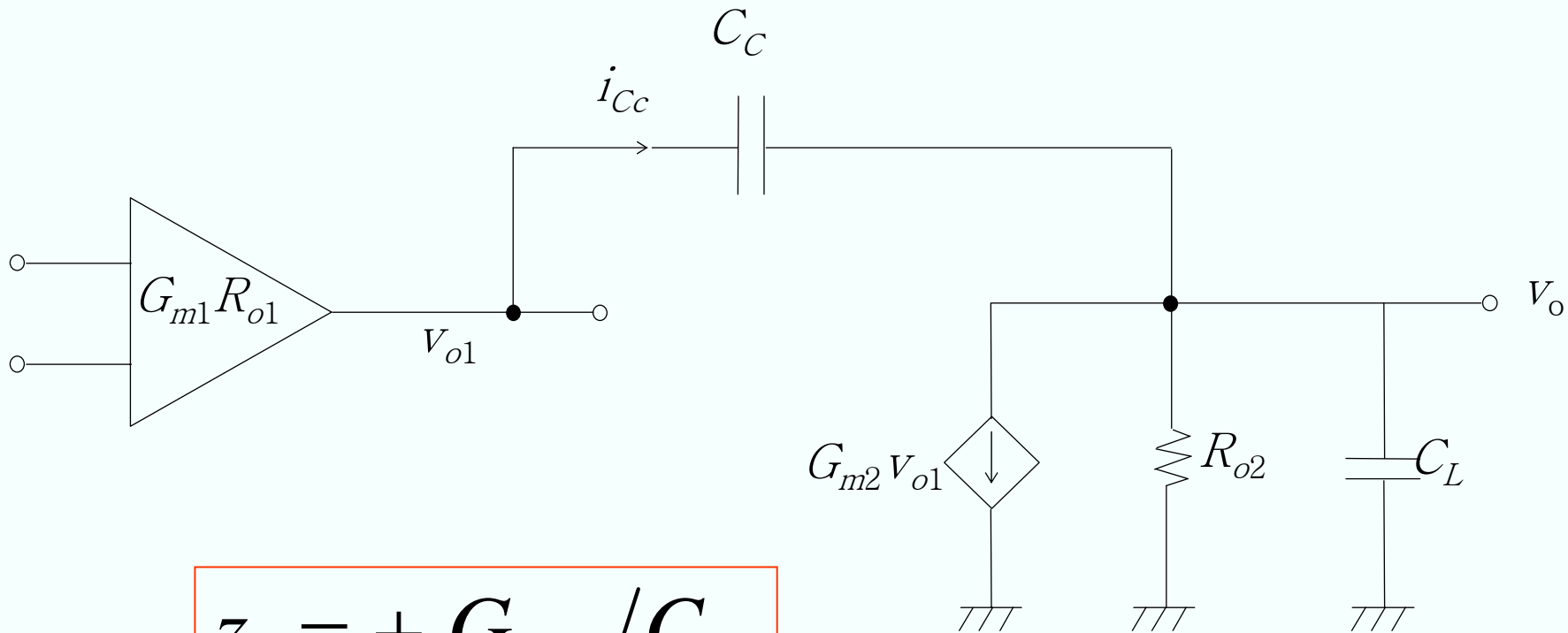
**If  $R_{o1}$  is small, even the cascade of two amps does not satisfy the above condition****→ Does not need frequency compensation****→ It is considered as a single-stage OP amp**

## positive real zero

Feed-forward through cap in an inverting amp

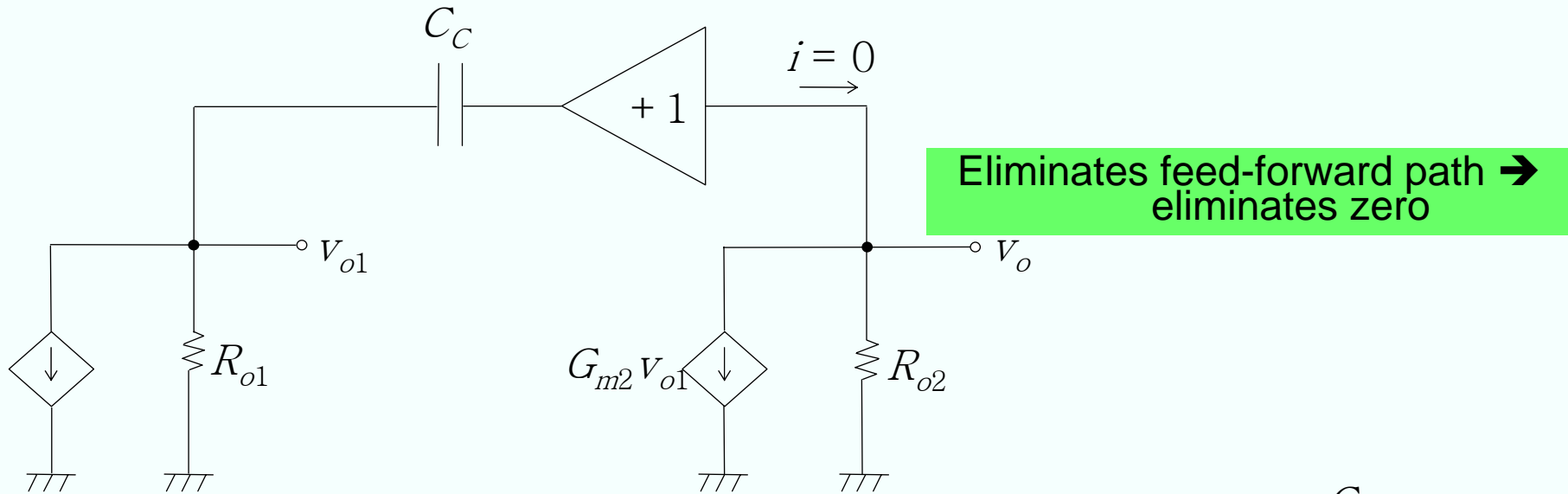
→ Positive real zero

→ Degrades phase margin

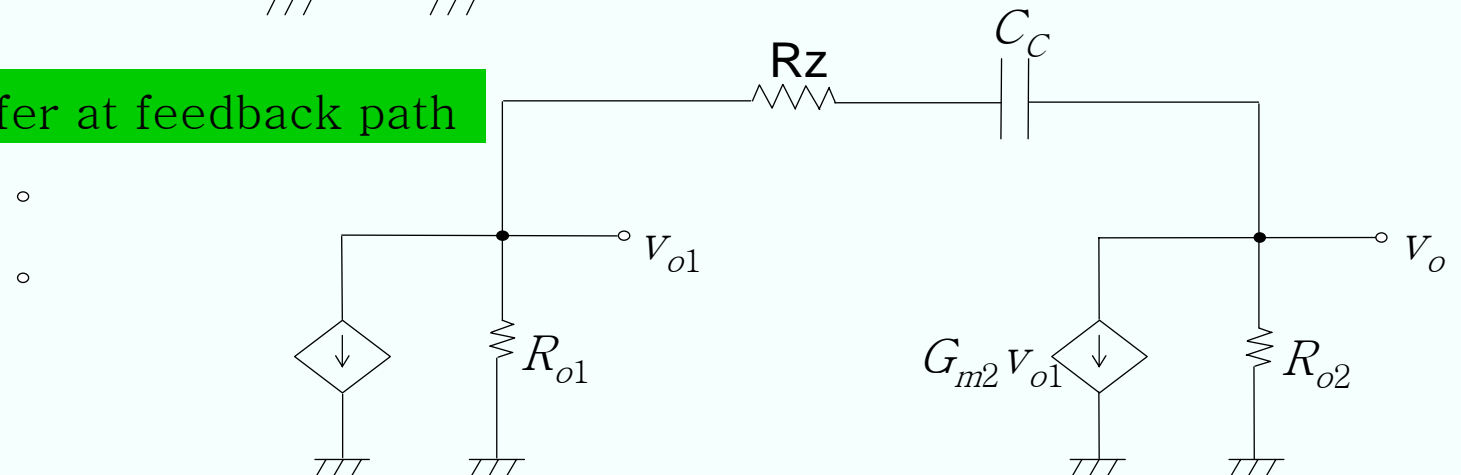


$$z_1 = + G_{m2}/C_C$$

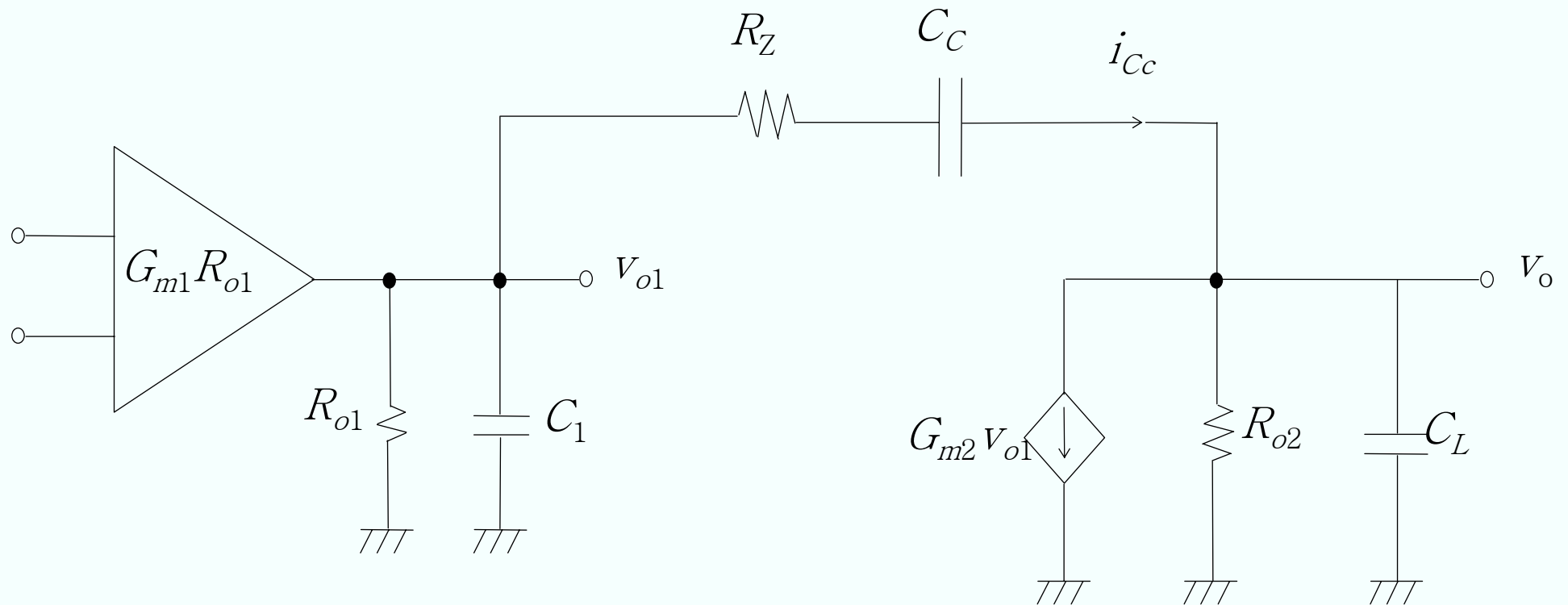
## Two methods to eliminate positive real zero



(a) A gain 1 voltage buffer at feedback path



(b)  $R_z (> 1/G_{m2})$  in series with  $C_c$



$$i_{C_c} = \frac{v_{o1}}{R_Z + \frac{1}{sC_C}} = G_{m2}v_{o1}$$

$$z_1 = \frac{G_{m2}}{C_C} \cdot \frac{1}{1 - G_{m2} \cdot R_Z}$$

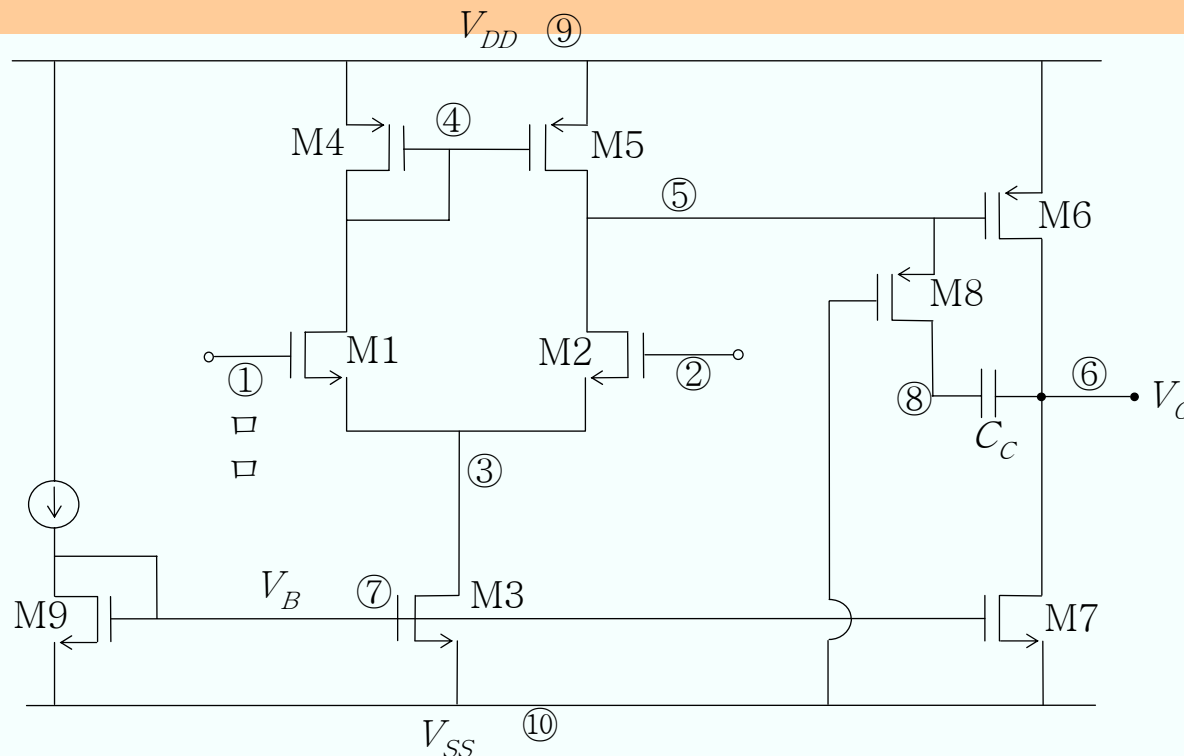
$R_Z > 1/G_{m2} \rightarrow$  changes feed-forward polarity  $\rightarrow$   
positive real zero changed to negative real zero

## Frequency compensation (SPICE simulation results)

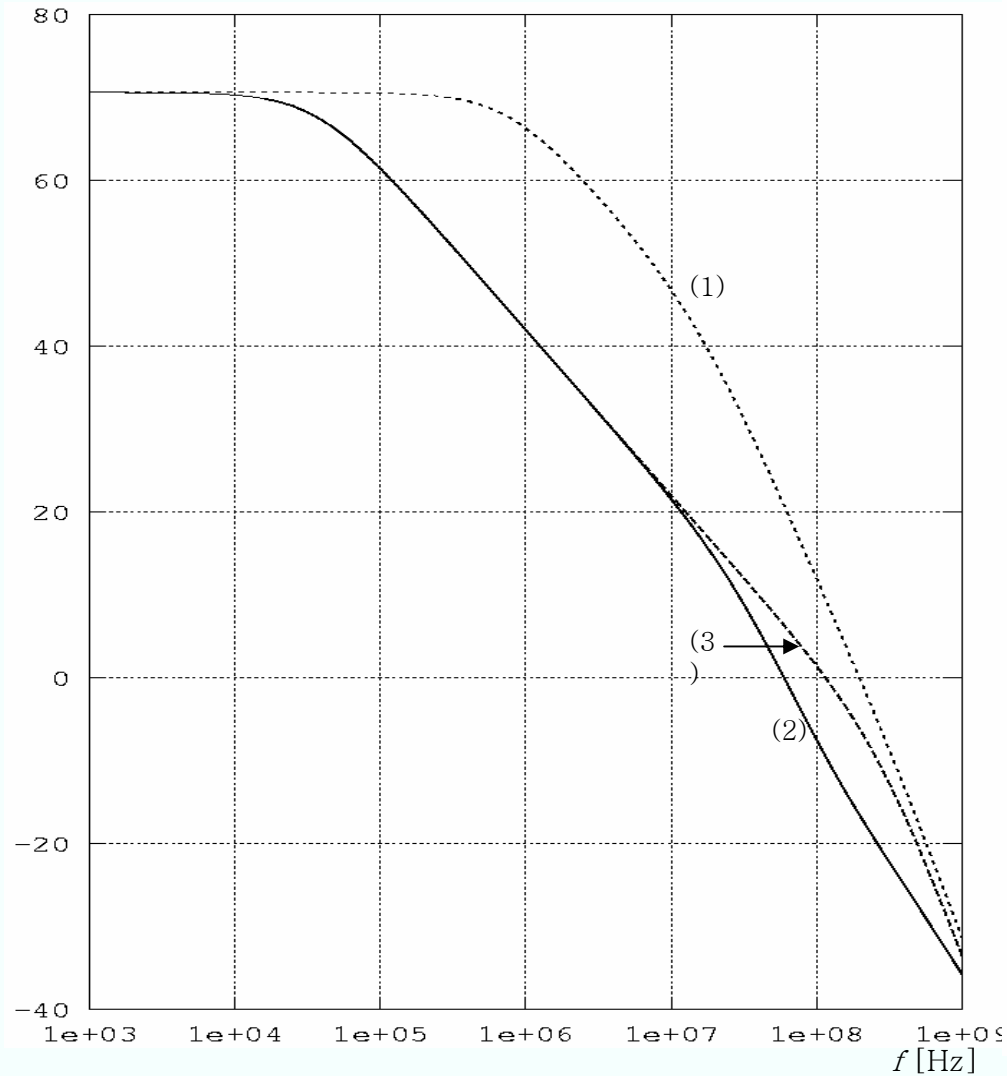
(1) No frequency compensation

(2) Frequency compensation with a  $2\text{pF}$  capacitor

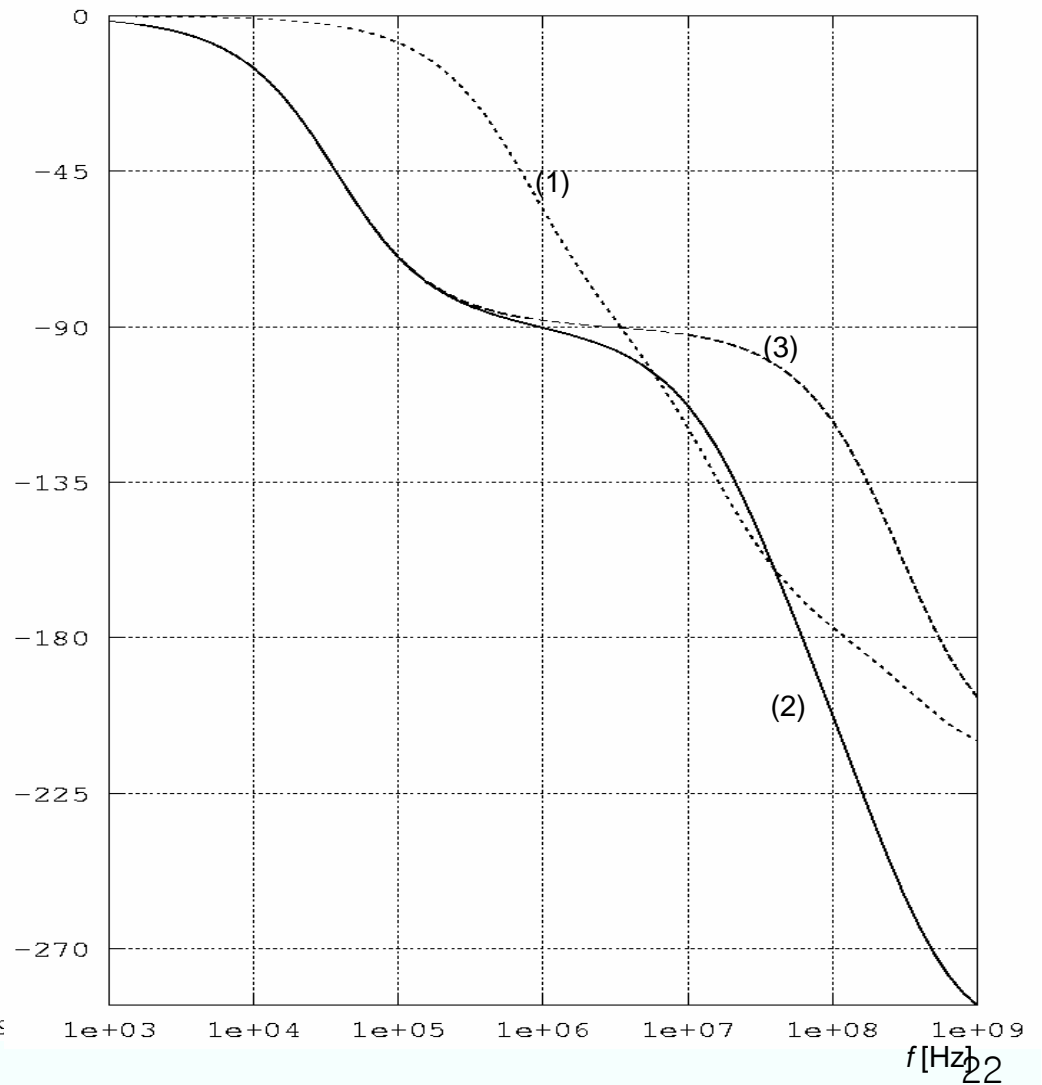
(3) Frequency compensation with a series connection of  $3.1\text{k}\Omega$  resistor and a  $2\text{pF}$  capacitor



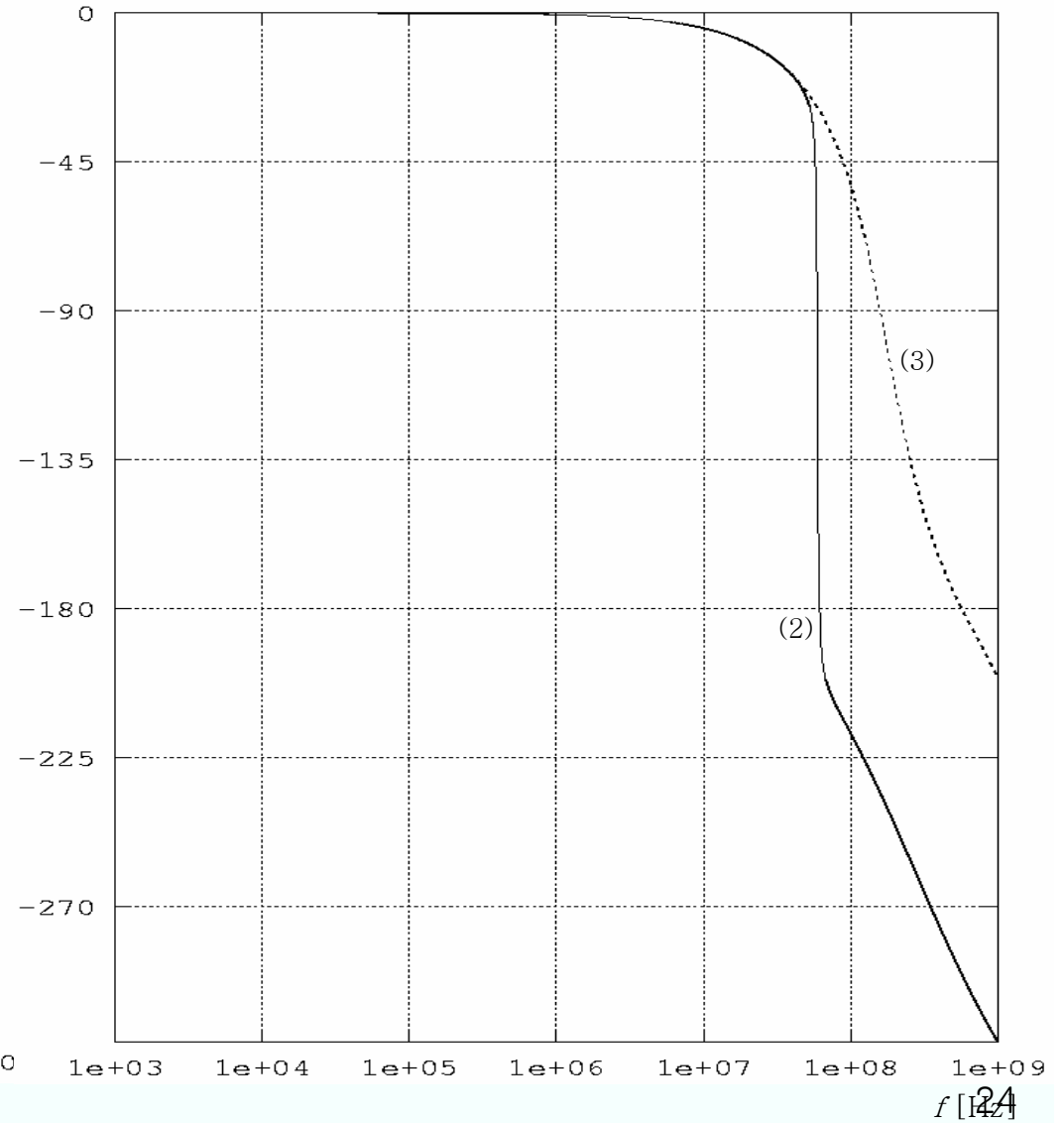
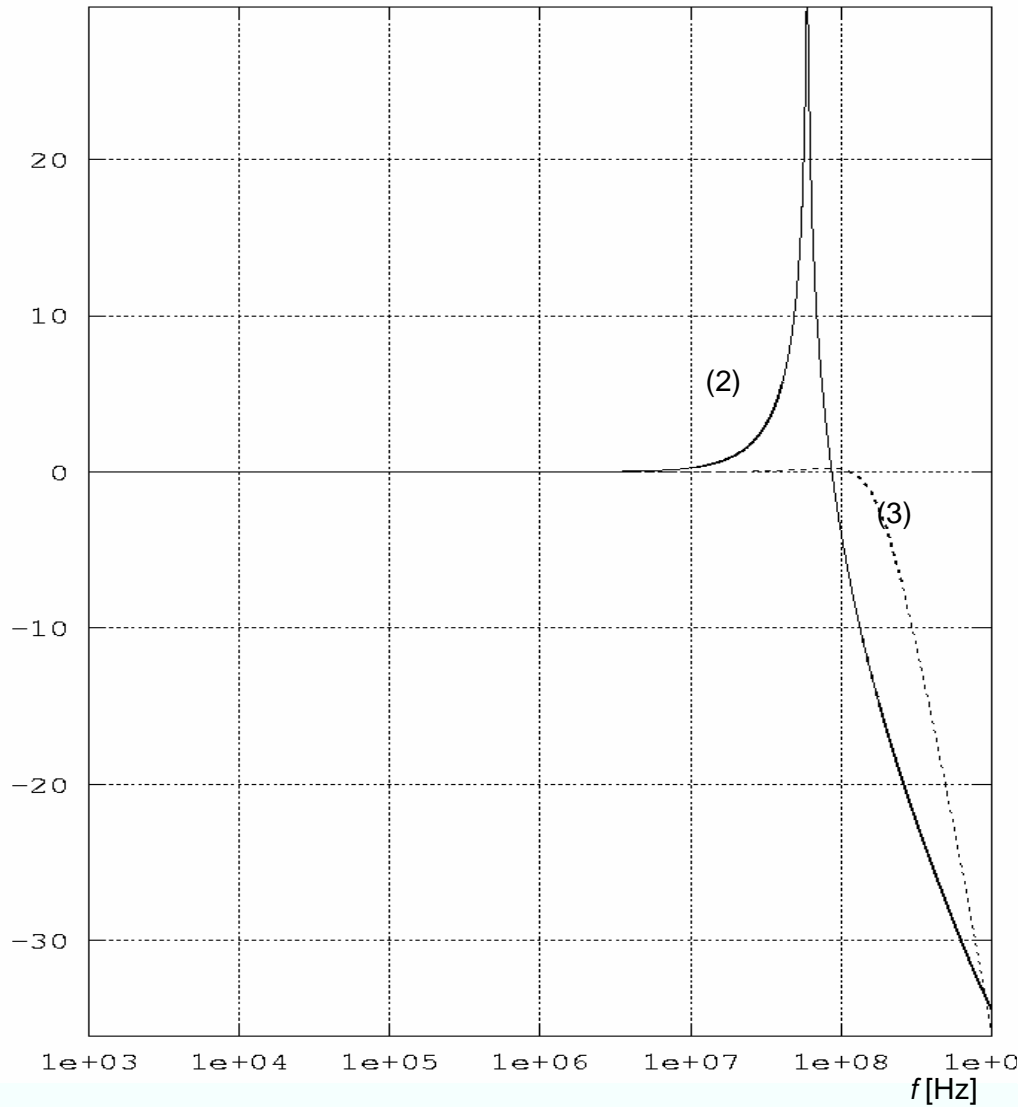
Magnitude  
[dB]

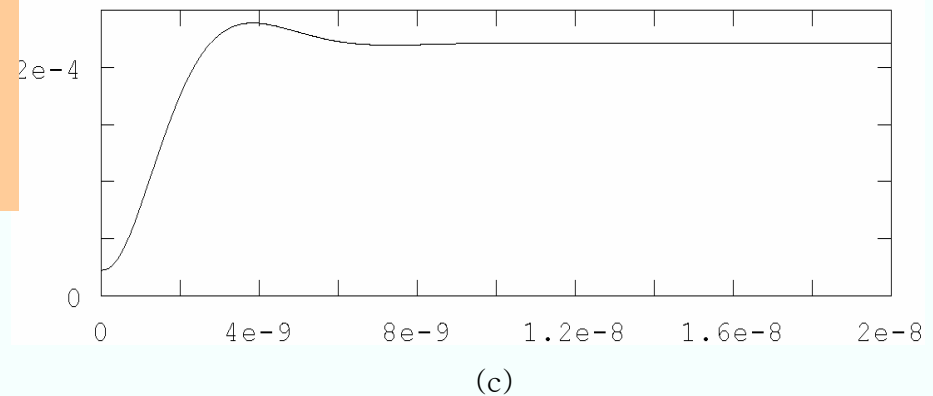
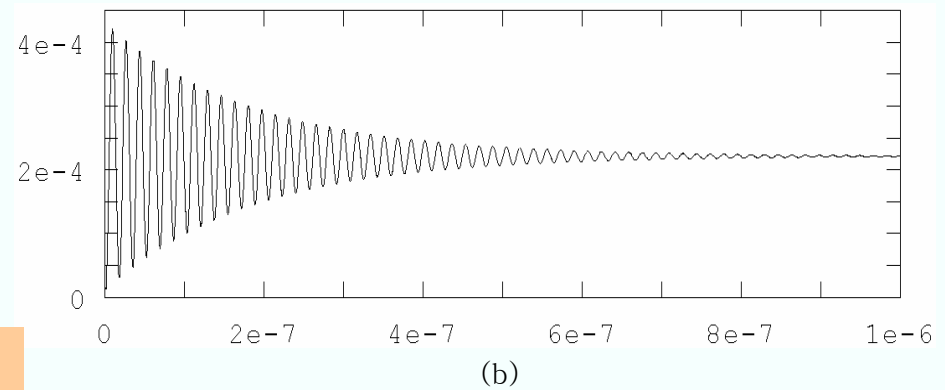
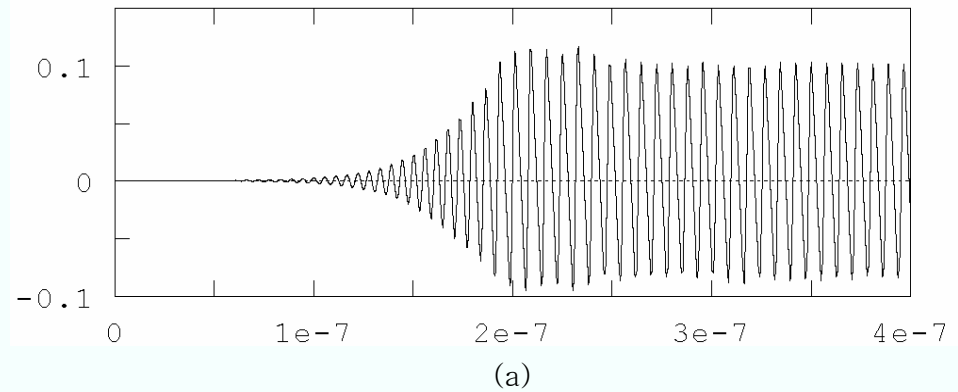
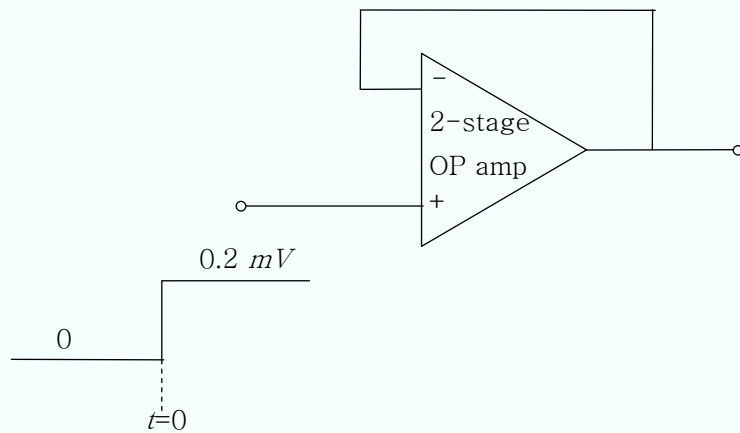


Phase  
[deg]



	$\frac{p_1}{2\pi}$	$\frac{p_2}{2\pi}$	$\frac{p_3}{2\pi}$	$\frac{z_1}{2\pi}$	$\frac{\omega_{0dB}}{2\pi}$	phase margin ( $f=1$ )
(1) No freq comp	-740 KHz	-16.5 MHz	-	-	125 MHz	$-7^\circ$
(2) Freq comp with Cc	-37 KHz	-30.7 MHz	-	+154 MHz	59.7 MHz	$+1.6^\circ$
(3) Freq comp with Rz, Cc	-37 KHz	-30.7 MHz	-160 MHz	-30.9 MHz	115 MHz	$+59^\circ$

Magnitude  
[dB]Phase  
[dB]



- (1) No freq compensation (PM = -7 deg)
- (2) Frequency compensation with a 2pF capacitor (PM = +1.6 deg)
- (3) Frequency compensation with a 3.1kohm resistor and a 2pF capacitor (PM = +59 deg)

$$A_{dv}(s) = \frac{A_{dv}(0) \cdot \left(1 - \frac{s}{z_1}\right)}{\left(1 - \frac{s}{p_1}\right) \cdot \left(1 - \frac{s}{p_2}\right)}$$

$$A_f(s) = \frac{A_{dv}(0)}{1 + A_{dv}(0)} \cdot \frac{1 - \frac{s}{z_1}}{1 - s \cdot \frac{1}{1 + A_{dv}(0)} \cdot \left(\frac{1}{p_1} + \frac{1}{p_2} + \frac{A_{dv}(0)}{z_1}\right) + \frac{s^2}{(1 + A_{dv}(0)) \cdot p_1 \cdot p_2}} \approx \frac{1 - \frac{s}{z_1}}{1 - s \cdot \left\{ \frac{1}{A_{dv}(0)} \cdot \left(\frac{1}{p_1} + \frac{1}{p_2}\right) + \frac{1}{z_1} \right\} + \frac{s^2}{A_{dv}(0) \cdot p_1 \cdot p_2}}$$

$$A_f(s) = \frac{1 - \frac{s}{z_1}}{1 + \frac{s}{\omega_o} \cdot \frac{1}{Q} + \frac{s^2}{\omega_o^2}}$$

$$\omega_o = \sqrt{A_{dv}(0) \cdot p_1 \cdot p_2}$$

$$Q = \frac{1}{\frac{-p_1 - p_2}{\omega_o} - \frac{\omega_o}{z_1}}$$

**Positive real zero: increase Q → less damped**

**Negative real zero: decrease Q → more damped**

$$V_O(s) = \frac{\Delta V_I}{s} \cdot \frac{1 - \frac{s}{z_1}}{1 + \frac{s}{\omega_o} \cdot \frac{1}{Q} + \frac{s^2}{\omega_o^2}} = \Delta V_I \cdot \left( \frac{1}{s} - \frac{\left( s + \frac{\omega_o}{2Q} \right) + \left( \frac{\omega_o}{2Q} + \frac{\omega_o^2}{z_1} \right)}{\left( s + \frac{\omega_o}{2Q} \right)^2 + \omega_o^2 \cdot \left( 1 - \frac{1}{4Q^2} \right)} \right)$$

$$v_O(t) = \Delta V_I \cdot u(t) \cdot \left( 1 - A_m \cdot e^{-\frac{\omega_o}{2Q} \cdot t} \cdot \sin(\omega_n t + \phi) \right)$$

$$\omega_n = \omega_o \cdot \sqrt{1 - \frac{1}{4Q^2}} \quad \phi = \tan^{-1} \left( \frac{\sqrt{1 - \frac{1}{4Q^2}}}{\frac{1}{2Q} + \frac{\omega_o}{z_1}} \right) \quad A_m = \frac{\sqrt{1 + \frac{\omega_o}{Qz_1} + \frac{\omega_o^2}{z_1^2}}}{\sqrt{1 - \frac{1}{4Q^2}}}$$

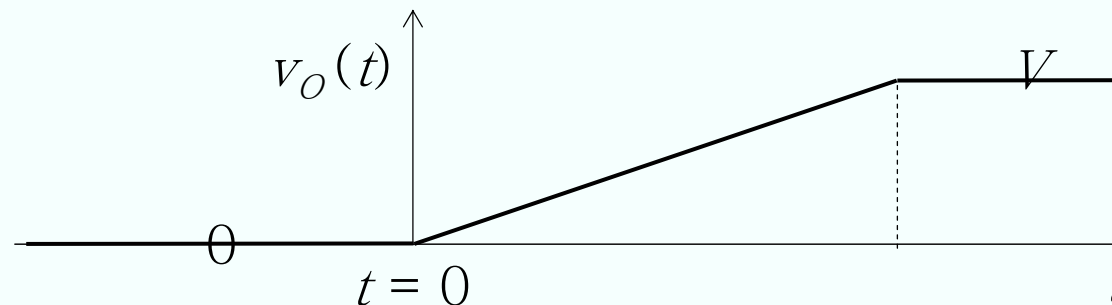
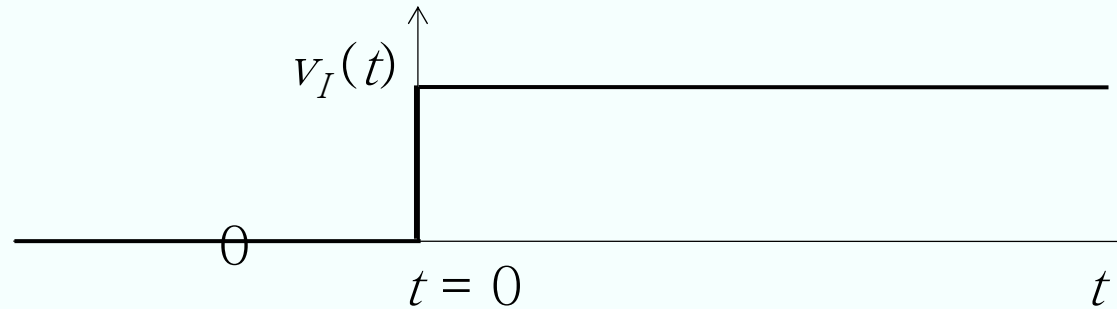
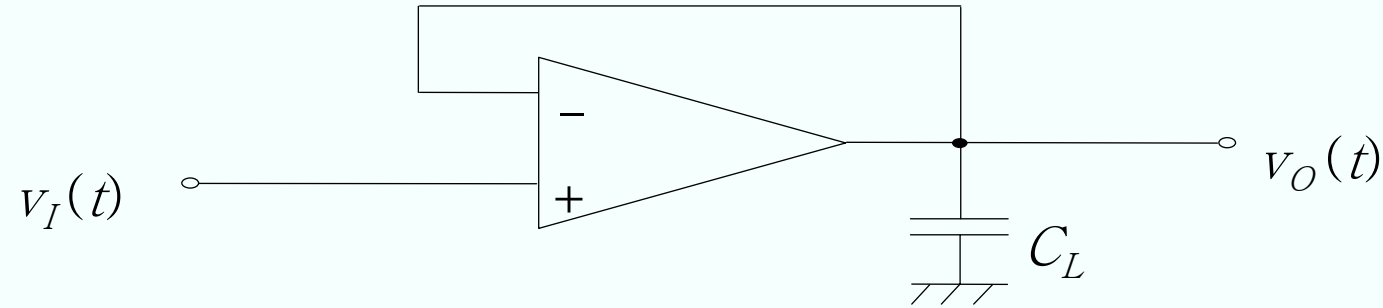
$$t_s = \frac{2Q}{\omega_o} \cdot \ln \left( \frac{A_m}{\varepsilon} \right)$$

increase Q → increase settling time

$$t_s = \frac{1}{\omega_T} \cdot \ln \left( \frac{1}{\varepsilon} \right)$$

Single pole case

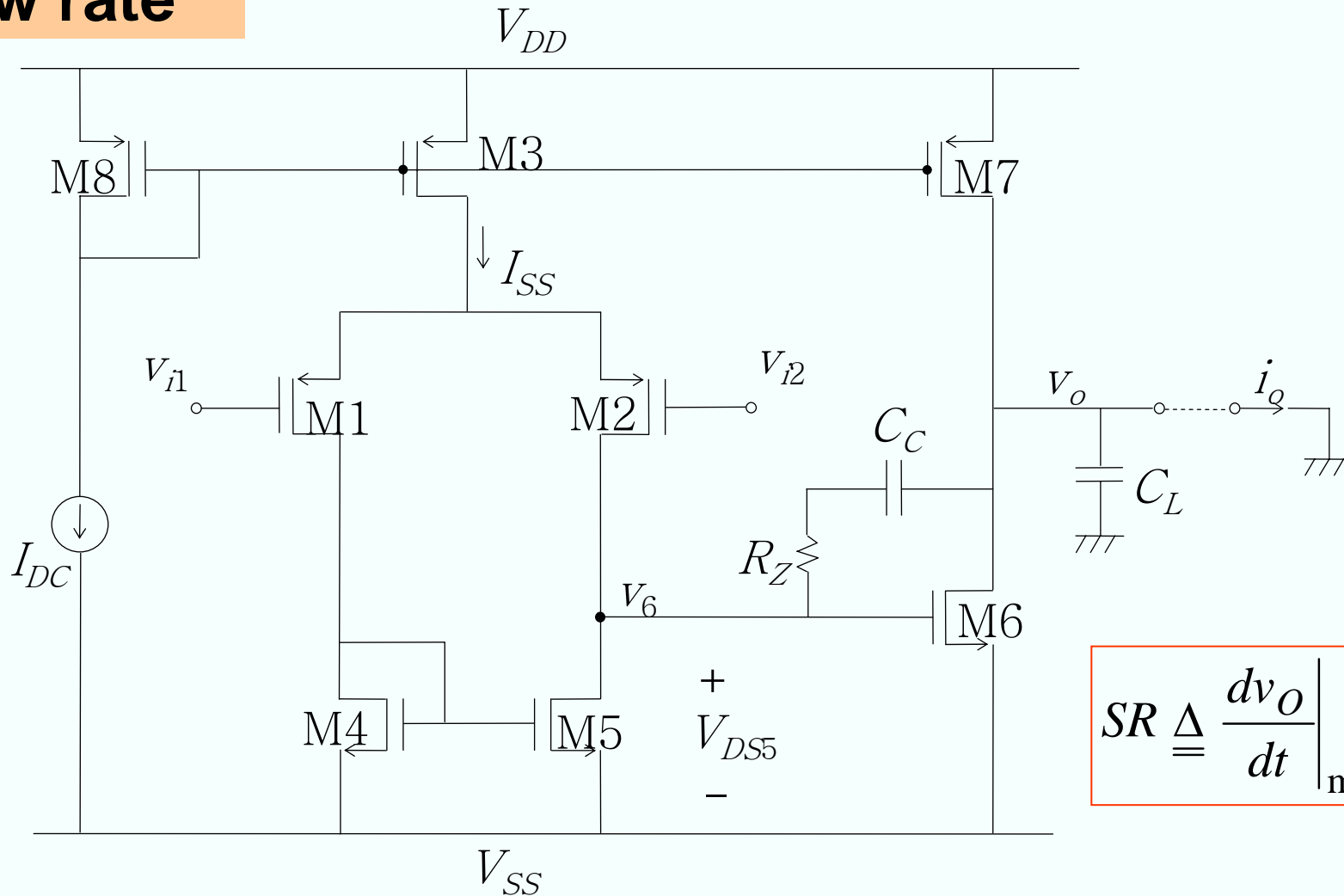
## Slew rate limitation due to $C_C$



$$SR \triangleq \left. \frac{dv_O}{dt} \right|_{\max} = \frac{I_{SS}}{C_C}$$

$$v_O(t) = (\text{Voltage across } C_C) + V_{DS5} + V_{SS} + I_{SS} R_Z = \frac{I_{SS}}{C_C} \cdot t + I_{SS} R_Z + v_O(t=0) = \frac{I_{SS}}{C_C} \cdot t + I_{SS} R_Z$$

## Slew rate



$$SR \triangleq \left. \frac{dv_O}{dt} \right|_{\max} = \frac{I_{SS}}{C_C}$$

$$v_O(t) = (\text{Voltage across } C_C) + V_{DS5} + V_{SS} + I_{SS} R_Z = \frac{I_{SS}}{C_C} \cdot t + I_{SS} R_Z + v_O(t=0) = \frac{I_{SS}}{C_C} \cdot t + I_{SS} R_Z$$

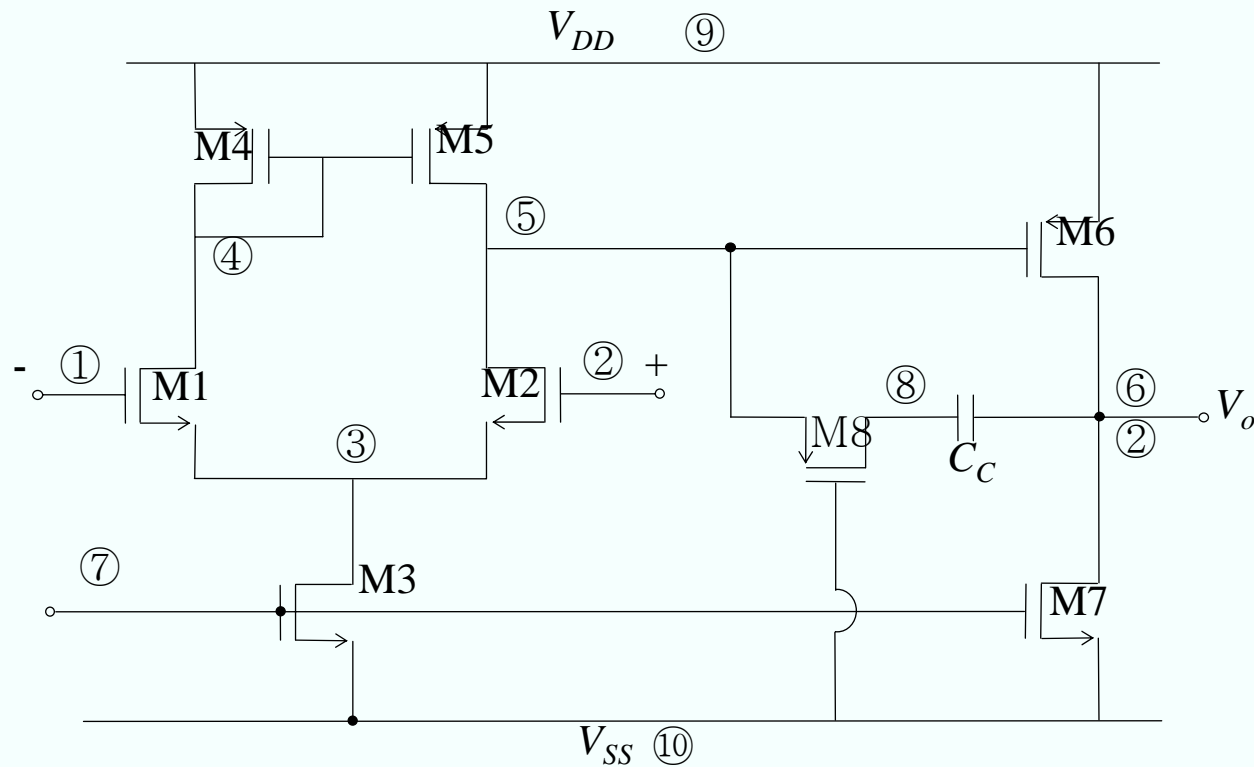
**FBBW (full power bandwidth): The maximum sine wave frequency with full amplitude without being distorted by slew rate phenomenon**

$$v_O(t) = V_m \cdot \sin(2\pi f_{FPBW} \cdot t)$$

$$\left. \frac{dv_O}{dt} \right|_{\max} = 2\pi f_{FPBW} \cdot V_m = SR$$

$$f_{FPBW} = \frac{SR}{2\pi V_m}$$

$$SR = \omega_T \cdot |V_{GS} - V_{TH}|_{1,2}$$



transistor	$W(\mu m)$
M1, M2	120
M3	20
M4, M5	20
M6	80
M7	40
M8	7

