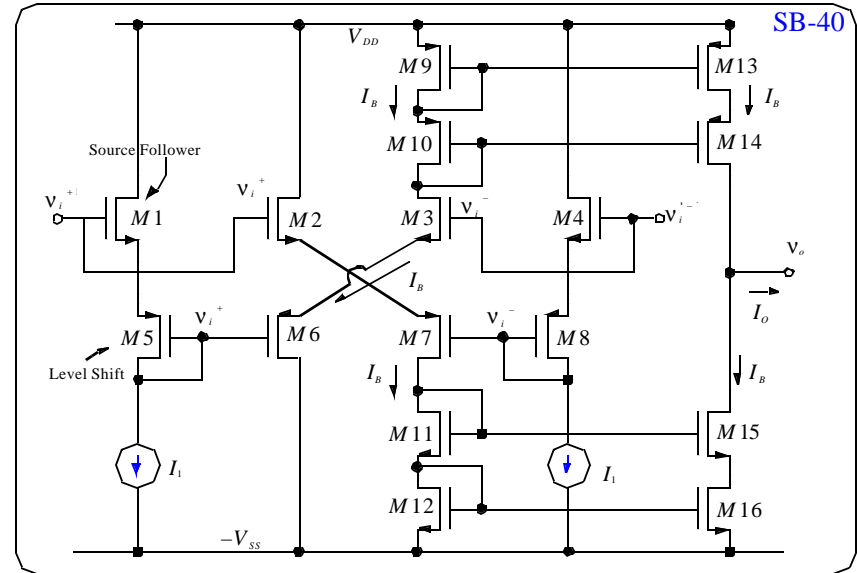


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Robert W. Brodersen
EECS140

Analog Circuit Design

Lectures
on
STABILITY
(continued)



SB-40

Class AB Input Stage Cross Coupled Differential Pair SB-41

Calculating currents :

$$V_{GS1} + V_{SG5} = V_{SG6} + V_{GS3} \quad v_i = 0$$

$$V_{Tn} + V_{DSAT1} + V_{Tn} + V_{DSAT5} = V_{Tn} + V_{DSAT1} + V_{Tp} + V_{DSAT3}$$

Let All

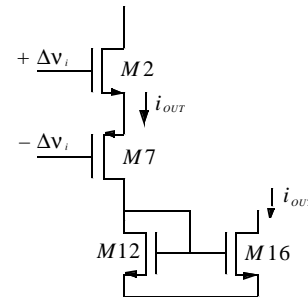
$$\left(\frac{W}{L}\right)_1 = \left(\frac{W}{L}\right)_3 \quad \left(\frac{W}{L}\right)_5 = \left(\frac{W}{L}\right)_6$$

$$\left(\frac{2 \cdot I_1}{\left(\frac{W}{L}\right)_5 \cdot k_p'}\right)^{\frac{1}{2}} + \left(\frac{2 \cdot I_1}{\left(\frac{W}{L}\right)_1 \cdot k_n'}\right)^{\frac{1}{2}} = \left(\frac{2 \cdot I_B}{\left(\frac{W}{L}\right)_5 \cdot k_p'}\right)^{\frac{1}{2}} + \left(\frac{2 \cdot I_B}{\left(\frac{W}{L}\right)_1 \cdot k_n'}\right)^{\frac{1}{2}}$$

$$I_1 = I_B$$

Class AB Input Stage Cross Coupled Differential Pair (Cont.) SB-42

Transistor M2 has M7 as its source resistance.



If g_m 's are all equal = g_m

$$\frac{g_{m2} \cdot v_i}{1 + g_{m2} \cdot \left(\frac{1}{g_{m7}}\right)} = \frac{g_{m2}}{2} \cdot \Delta v_i = \frac{g_m}{2} \cdot \Delta v_i$$

Class AB Input Stage Cross Coupled Differential Pair (Cont.) SB-43

As Δv_i increase i_{out} continues to increase.

If Δv_i decreases M2 & M7 cutoff.

But then current comes from M3 & M6.

So for Small Signals

$$GM = \frac{i_{ds3}}{v_{in}} + \frac{i_{ds7}}{v_{in}} = g_m$$

$g_m/2$

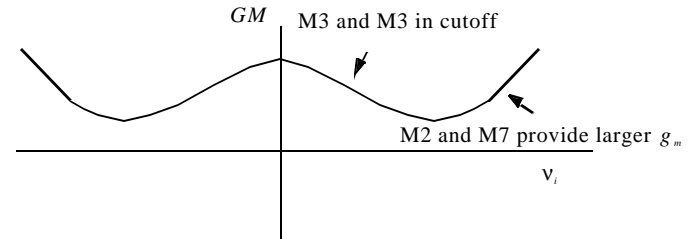
$$R_{out} = g_m \cdot r_o^2 \parallel g_m \cdot r_o^2 = \frac{g_m \cdot r_o^2}{2}$$

$$A_v = \frac{g_m^2 \cdot r_o^2}{2}$$

SB-44

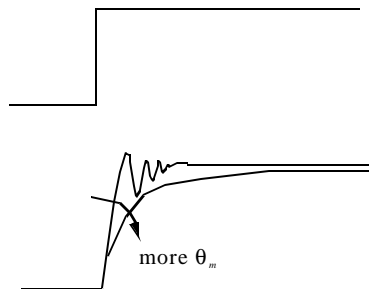
Class AB Input Stage Cross Coupled Differential Pair (Cont.)

For Large Signals either M2, M9 or M3, M6 cutoff so the g_m drops, but since the current is increasing it increases again.



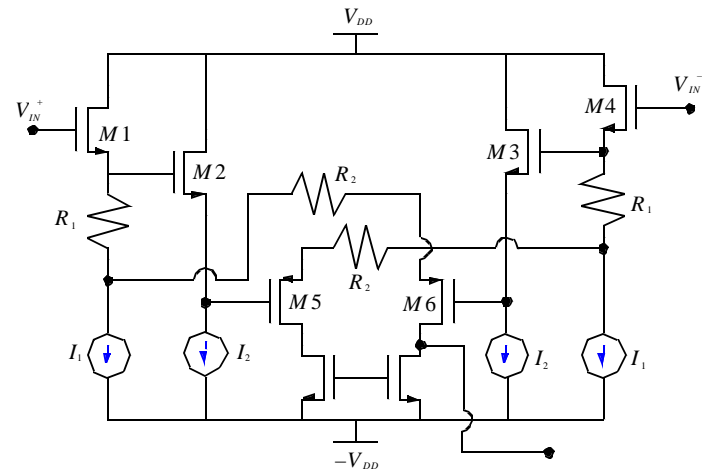
Class AB Input Stage Cross Coupled Differential Pair (Cont.) SB-45

Slew Rates can be very high since they are independent of the Bias Current \Rightarrow Bigger Signal gives more current to drive the next stage.



SB-46

Another Class AB



Another Class AB (Cont.)

SB-47

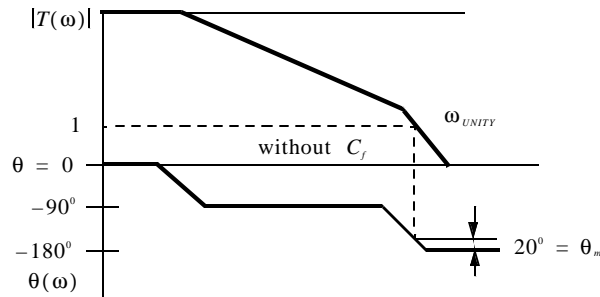
Small Signals M5 & M6 are degenerated by R_1 & R_2

But for Large Signals the INPUT appears across $R_1 + R_2$

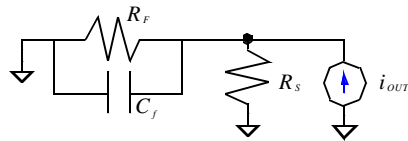
$$I_{OUT} = \frac{V_{IN^+} - V_{IN^-}}{R_1 + R_2}$$

Feedback Zero Compensation (Cont.)

SB-49

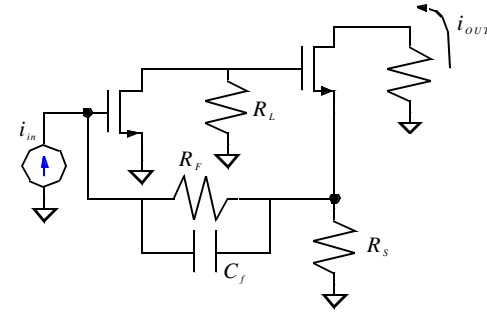


But we want 45° of θ_m so we add C_f



Feedback Zero Compensation

SB-48



Shunt - Series Feedback

Feedback Zero Compensation (Cont.)

SB-50

$$f = \frac{R_s}{R_f + R_s} \cdot \left(\frac{1 + R_f \cdot j \cdot \omega \cdot C_f}{1 + (R_s \parallel R_f) \cdot j \cdot \omega \cdot C_f} \right)$$

If $R_s \ll R_f$

$$f = \frac{R_s}{R_f} \cdot \left(\frac{1 + j \cdot \omega \cdot R_f \cdot C_f}{1 + j \cdot \omega \cdot R_s \cdot C_f} \right)$$

$$\omega_z = \frac{1}{R_f \cdot C_f} \quad \omega_p = \frac{1}{R_s \cdot C_f}$$

Since $R_s \ll R_f$ $\omega_z \ll \omega_p$

$$T = a(\omega) \cdot f(\omega)$$

Feedback Zero Compensation (Cont.)

SB-51

We can add positive phase shift from the zero at ω_{unity} and as long as the contribution is $< 45^\circ$ There is no change in the magnitude of $f(\omega)$ and thus $T(\omega)$

$$\tan(\omega_{\text{UNITY}}(R_f \cdot C_f)) = 25^\circ$$

or,

$$C_f = \frac{1}{R_f \omega_{\text{UNITY}}} \cdot \arctan(25^\circ)$$

